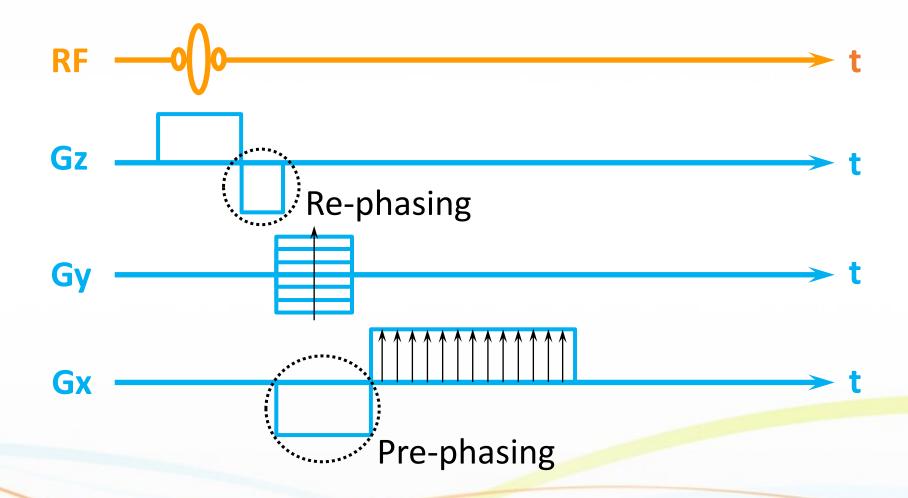
Pulse sequence

- Waveforms of gradients and RF pulses
- All scanning parameters is determined by the waveform
 - Slice selection
 - Phase encoding
 - Frequency encoding

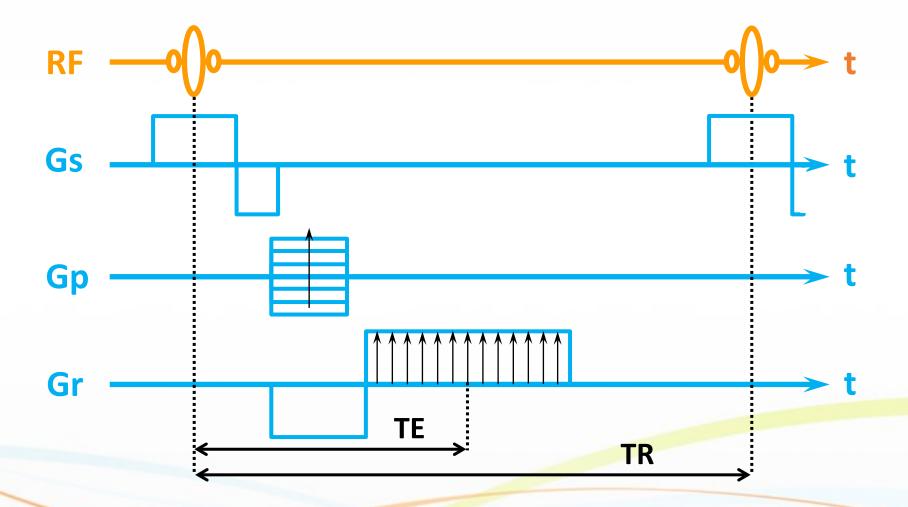
How to determine scan parameters?

- Slice thickness
- Field of view (FOV)
- Pixel width/Matrix size
 - Frequency encoding, or readout encoding
 - Phase encoding

Gradient echo



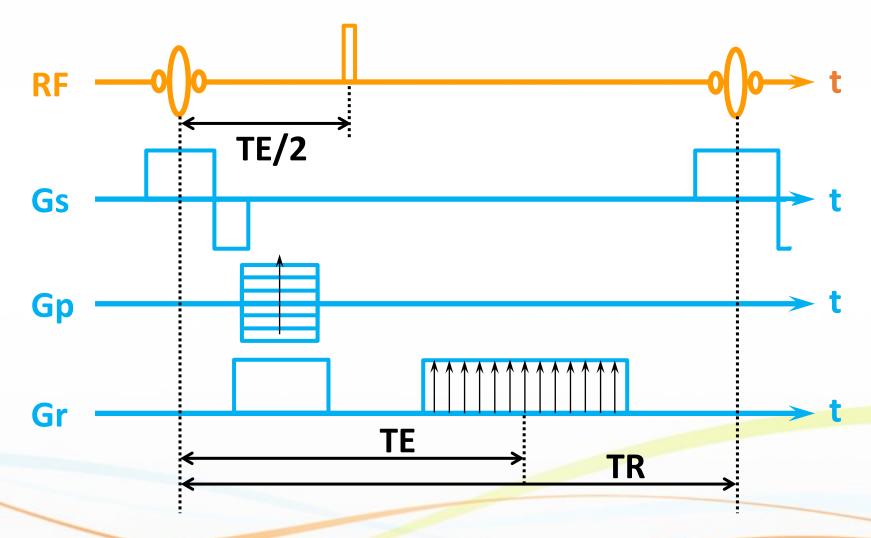
Gradient echo



Gradient echo

- Phase encoding gradient is altered in every TR for sufficient sampling
- Scan time = N_{PE} x TR
- Image contrast is basically determined by TE and TR
- How about spin echo?

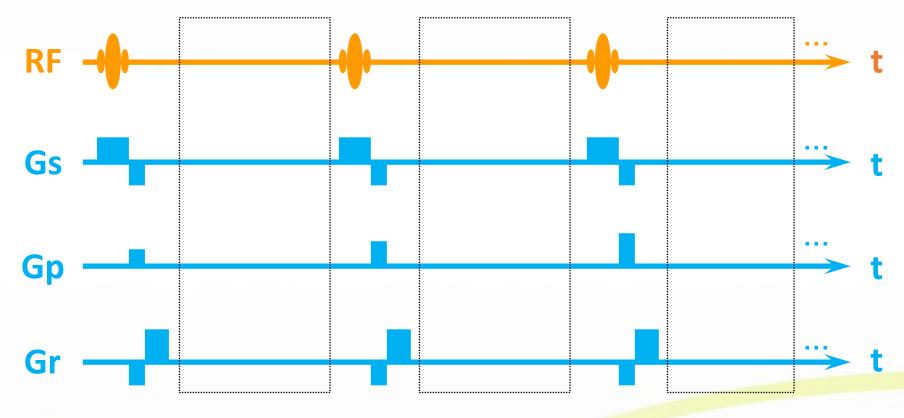
Spin echo



Imaging in 3D space

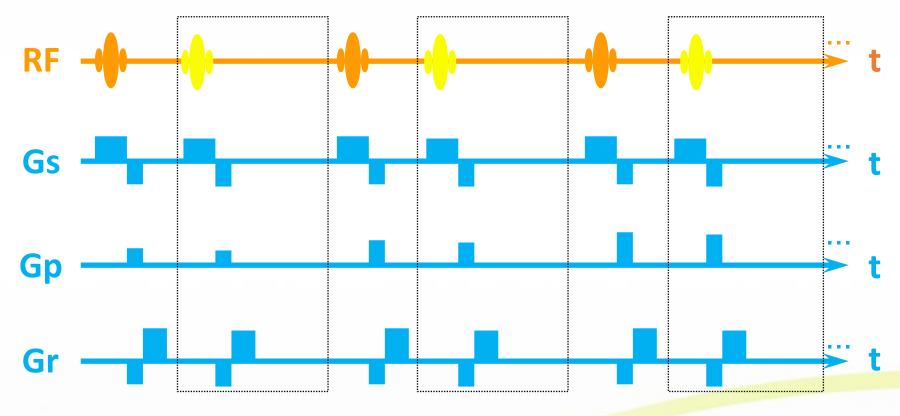
- 2D image suitable for human vision
 - Limited information
- Multi-slice imaging is favored to increase spatial coverage.
- Scan one slice after another?

Pulse sequence of more TR cycles...



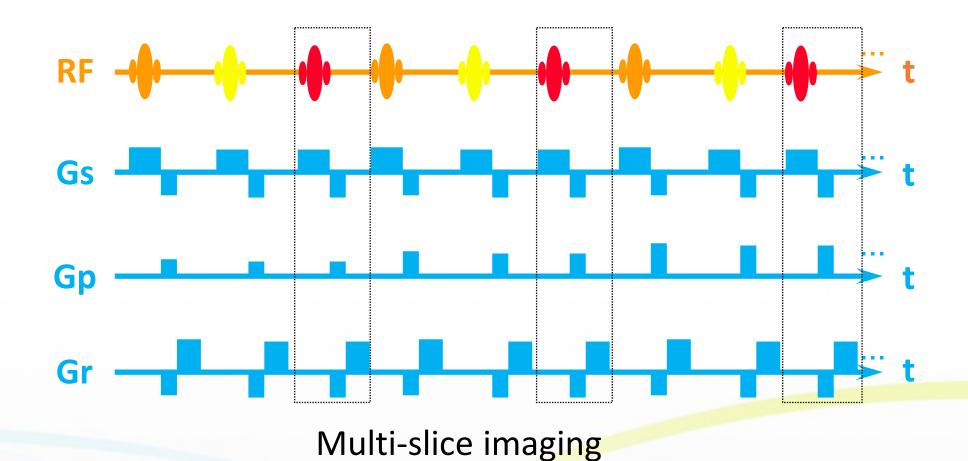
TE >> TR: do nothing for most of time

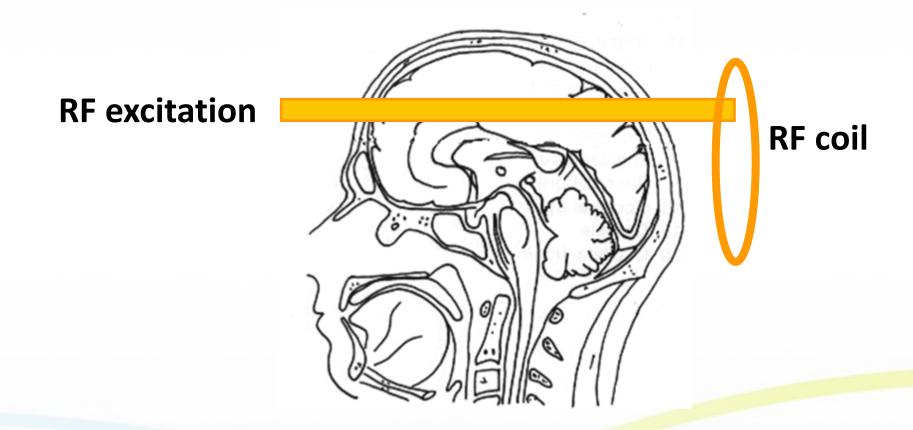
Insertion of another slice



Taking advantage of the spare time

Insertion of one another slice again

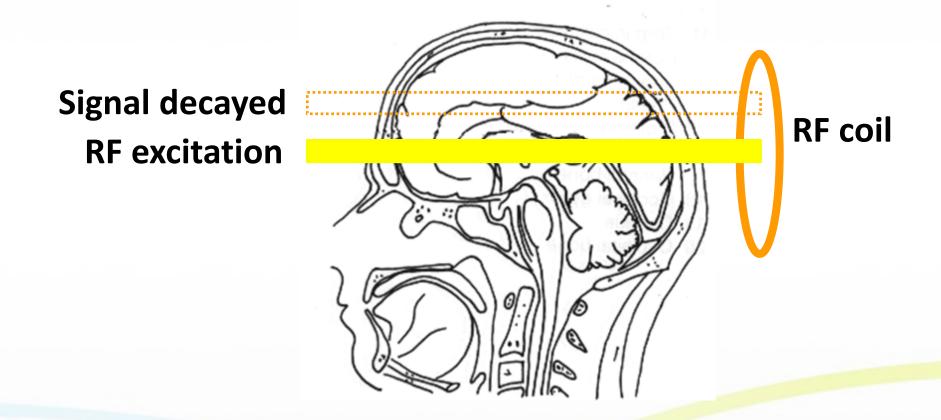




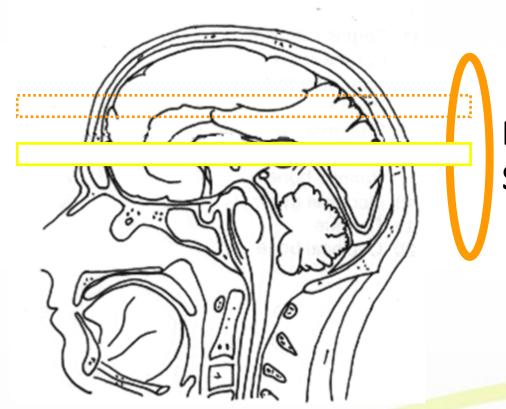
Signal induction and decay



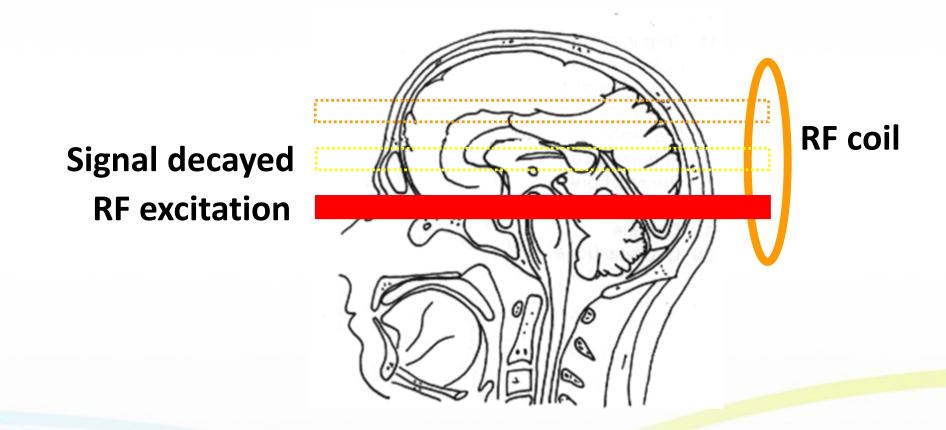
RF coil
Signal reception



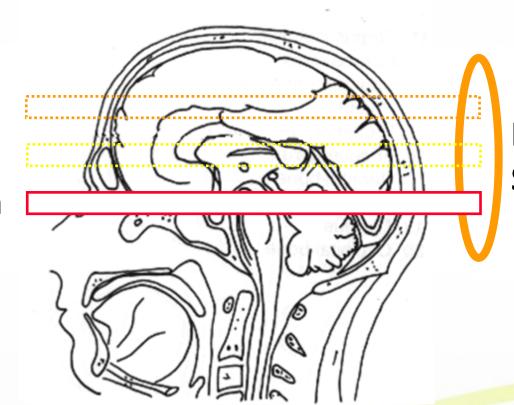
Signal induction and decay



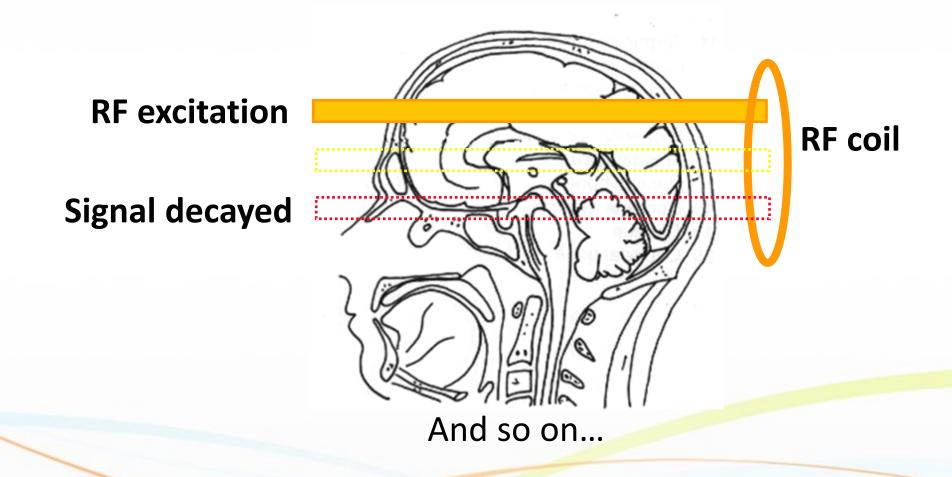
RF coil
Signal reception



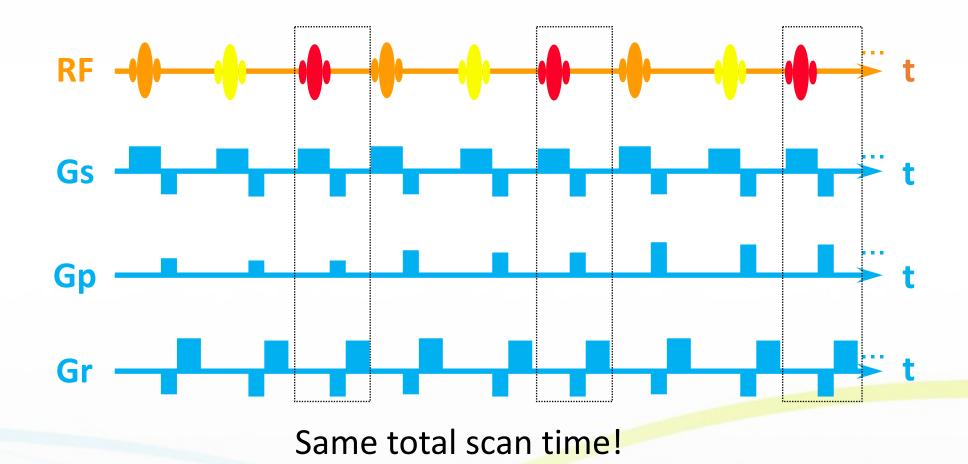
Signal induction and decay



RF coil
Signal reception



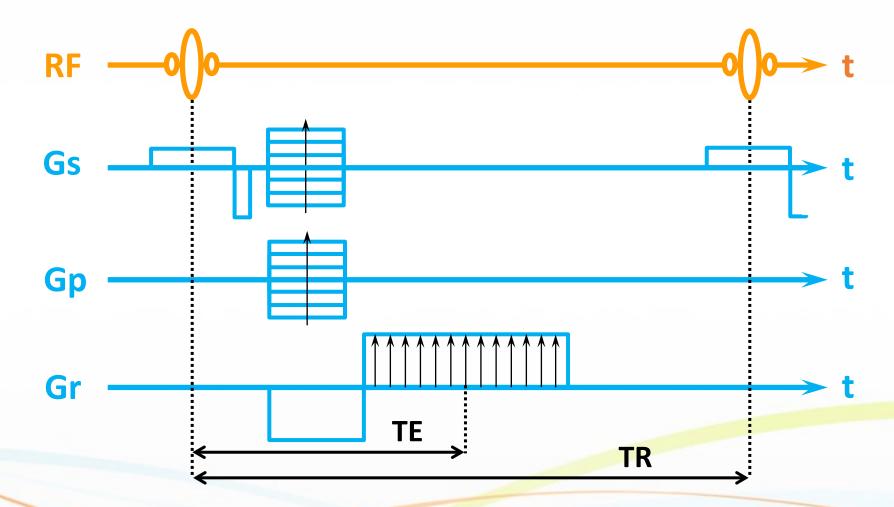
Multi-slice pulse sequence



3D MRI

- Extend 2D encoding to 3D encoding
- Two sets of independent phase encodings
- 2D-FT → 3D-FT
- No gap between adjacent slices

3D Gradient echo



3D MRI

- Excitation of a thick slab
 - Excitation pulse duration can be shortened.
 - So is minimal TE.
 - Only meaningful for ultra-short TE imaging
- Scan time = $N_{PE} \times N_{SPE} \times TR$
 - Not practical unless TR is short enough

Basic Principles of MRI